CONTINUOUS SELECTIONS OF NON-LOWER SEMICONTINUOUS NONCONVEX-VALUED MAPPINGS

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1. Introduction

While lower semicontinuity of mappings with closed convex values is sufficient for the existence of continuous singlevalued selections, it is of course, not necessary. For example, one can start by an arbitrary continuous singlevalued mapping $f: X \to Y$ and then define F(x) to be a subset of Y such that $f(x) \in F(x)$. Then F admits the selection f, but there are no continuity type restrictions for F. A very natural problem immediately arises. Namely, to find a weaker version of lower semicontinuity which preserves the existence of singlevalued selections. If we can find a lower semicontinuous selection G of a given convex-valued mapping F, then Michael's techniques can be used to find a continuous selection f of a lower semicontinuous mapping Cl(conv(G)) (see [7] or [14]). Moreover, any selection of Cl(conv(G)) will automatically be a selection of F. The situation is more complicated for the case of nonconvex-valued mappings F.

The notion of the function of nonconvexity of a closed subset of a Banach space was first introduced in [11]. In this paper we consider mappings F whose

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values F(x) have some common non-decreasing majorant $\alpha:(0,\infty)\to[0,1)$ for their functions of nonconvexity. In this situation, we have in general, no information about "nonconvexity" of the values G(x) for a lower semicontinuous selection G of F. So we replace the property "F admits a lower semicontinuous selection" by the property "F admits a sufficiently large family of lower semicontinuous selections". The formalisation of the last property leads us to introduce some new classes of non-lower semicontinuous mappings.

We denote by D(y,r) the open ball of radius r, centered at an arbitrary point y of a metric space Y. For any subset $A \subset Y$, we put $D(A,r) = \bigcup \{D(y,r) \mid y \in A\}$ and $D(A,\infty) = Y$. For two multivalued mappings F_1 and F_2 from X into Y we denote by $F_1 \cap F_2$ the mapping $x \mapsto F_1(x) \cap F_2(x)$. For a multivalued mapping $F: X \to Y$ into a metric space Y and for a real-valued mapping $d: X \to (0,\infty)$ we denote by D(F,d) the multivalued mapping $x \mapsto D(F(x),d(x))$. For a closed-valued mapping $F: X \to Y$ into a metric space Y and for a real-valued mapping $\varepsilon: X \to (0,\infty)$ we say that a continuous singlevalued mapping $f: X \to Y$ is an ε -selection of F, whenever $\varepsilon(\cdot)$ is a strong majorant of $\mathrm{dist}(f(\cdot),F(\cdot))$, i.e. $\varepsilon(x) > \mathrm{dist}(f(x),F(x))$, for every $x \in X$. We use the term function for singlevalued mappings with values from \mathbb{R} .

Definition 1.1. Let $\lambda:(0,\infty)\to [1,\infty)$ be any function. Then a closed-valued mapping $F:X\to Y$ to a metric space Y is said to be an LS_{λ} -mapping if for every continuous function $\varepsilon:X\to (0,\infty)$ and every continuous ε -selection f of F, the multivalued mapping $\operatorname{clos}(F\cap D(f,\lambda(\varepsilon)\cdot\varepsilon))$ admits a lower semicontinuous selection.

Each lower semicontinuous mapping F is an LS_1 -mapping because the intersection $F \cap D(f,\varepsilon)$ is lower semicontinuous. Clearly, each LS_{λ} -mapping is an LS_{μ} -mapping, whenever $\lambda \leq \mu$. Next, LS_{∞} -mappings are exactly those which admit lower semicontinuous selections. We chose the notation LS_{λ} -mapping as an abbreviation for "mappings, having lower semicontinuous selections with respect to the λ -enlargement of open balls".

Theorem 1.2. Let $\alpha:(0,\infty)\to [0,1)$ and $\lambda:(0,\infty)\to [1,\infty)$ be any functions such that λ is locally bounded at the origin and $t\mapsto \alpha(\lambda(t)\cdot t)\cdot \lambda(t)$ has a nondecreasing strong majorant $M:(0,\infty)\to [0,1)$. Then every LS_{λ} -mapping from a paracompact space X into a Banach space Y admits a single-valued continuous selection, whenever $\alpha(\cdot)$ is a majorant of the set of functions of nonconvexity of values F(x), for every $x\in X$.

For constants α and λ , the hypotheses of Theorem 1.2 are guaranteed by the inequality $\alpha \cdot \lambda < 1$. For the constant λ it suffices to assume that the set of all

functions of nonconvexity of values F(x), $x \in X$, has a nondecreasing majorant $\alpha:(0,\infty)\to[0,1)$. Various weakenings of lower semicontinuity of convex-valued mappings for which a continuous singlevalued selections exist (as in the classical situation) have been intensively studied in the series of papers [1], [2], [5], [6], [9] (see also [10] and [14], § II.3). Most of them are related to the behaviour of a different kind of derived mappings (F', F_0, F_ε) of a given mapping. For the class of so-called *quasi-lower semicontinuous* mappings (see Definition 2.2 below), the derived mapping F' in the sense of Brown [3] is the largest possible lower semicontinuous selection of F. For *convex-valued* quasi l.s.c. mappings and for a *constant* λ , a property somewhat similar to our Definition 1.1 was obtained in [9]. We state the following fact related to Definition 1.1:

Theorem 1.3. Every quasi-lower semicontinuous mapping of a paracompact space into a complete metric space is an LS_{λ} -mapping, for each continuous realvalued function $\lambda:(0,\infty)\to(1,\infty)$.

We derive the following theorem from Theorems 1.2 and 1.3.

Theorem 1.4. Let $\alpha:(0,\infty)\to [0,1)$ be a nondecrasing function. Then every quasi-lower semicontinuous mapping F from a paracompact space X into a Banach space admits a singlevalued continuous selection, whenever $\alpha(\cdot)$ is a majorant of the set of functions of nonconvexity of values F(x), for every $x\in X$.

We list some special cases of Theorem 1.4. For $\alpha(\cdot) \equiv 0$ and any l.s.c. mapping F it yields the Michael convex-valued selection theorem [7]. For $\alpha(\cdot) \equiv q < 1$ and any l.s.c. mapping F we get the Michael paraconvex-valued selection theorem [8]. For $\alpha(\cdot) \equiv 0$ and weakly Hausdorff l.s.c. F (respectively, weakly l.s.c. or quasi l.s.c. F) it gives the DeBlasi-Myjak's (respectively, Przeslawski-Rybinski's or Gutev's) selection theorem [2], [5], [6], [9]. For any nondecreasing function α and for any l.s.c. F it yields a theorem proved earlier by these authors [11], [17]. As an application to the theory of fixed-points of multivalued contractions we can also obtain the following generalization of Ricceri's result [15], in the spirit of the Rybinski paper [16].

Theorem 1.5. Let X be a paracompact space, Y a Banach space and $X \times Y$ a paracompact space. Suppose that for a multivalued mapping $F: X \times Y \to Y$ and some constants α and γ from [0,1) the following properties hold:

- (a) Functions of nonconvexity of all values F(x,y) are less than or equal to α .
- (b) Each mapping $F(x, \cdot)$ is a γ -contraction,
- (c) Each mapping $F(\cdot,y)$ is quasi-lower semicontinuous, and
- (d) $\alpha + \gamma < 1$.

Then there exists a singlevalued continuous mapping $f: X \times Y \to Y$ such that for every $x \in X$, the restriction $f(x, \cdot)$ is a retraction onto the fixed-point set of the contraction $F(x, \cdot)$.

2. Preliminaries

We begin by a construction of a function of nonconvexity. For any nonempty closed subset $P \subset Y$ of a Banach space Y and for any open r-ball $D_r \subset Y$, we define the *relative precision* of an approximation of P by elements of D_r as follows:

$$\delta(P,D_r) = \sup \left\{ \frac{\operatorname{dist}(q,P)}{r} \mid q \in \operatorname{conv}(P \cap D_r) \right\}.$$

Clearly, for a convex set P with nonempty intersection $P \cap D_r$, the equality $\delta(P, D_r) = 0$ means that this intersection is a convex subset of P.

Definition 2.1. For a nonempty closed subset $P \subset Y$ of a Banach space Y, the function $\alpha_P(\cdot)$ of nonconvexity of P associates to each positive number r the following nonnegative number:

$$\alpha_P(r) = \sup \{ \delta(P, D_r) \mid D_r \text{ runs over all open } r\text{-balls} \}.$$

Clearly, the identical equality $\alpha_P(\cdot) \equiv 0$ is equivalent to *convexity* of the closed set P. Following Michael [8], the set P is said to be q-paraconvex, whenever the number q is a majorant of the function $\alpha_P(\cdot)$. A selection theorem for q-paraconvex valued l.s.c. maps, q < 1, was proved in [8]. For a possible substitute of a suitable function $q(\cdot)$ instead of the constant see [11]. For examples of classes of closed sets with nice functions of nonconvexity see [12], [13], [19].

The notion of quasi lower semicontinuity (respectively, weak lower semicontinuity) of a multivalued mapping was introduced in [5], [6] (respectively, in [9]). Recall, that for a multivalued mapping $F: X \to Y$, the preimage $F^{-1}(A)$, $A \subset Y$, is defined as $\{x \in X \mid F(x) \cap A \neq \emptyset\}$ and for topological spaces X and Y, a mapping F is said to be *lower semicontinuous* if preimages of open sets are open sets.

Definition 2.2. A multivalued mapping $F: X \to Y$ of a topological space X into a metric space (Y, ρ) is said to be *quasi lower semicontinuous* if for every triple $(x, U(x), \varepsilon)$, where $x \in X$, U(x) is a neighborhood of x and $\varepsilon > 0$, there exists a point $q(x) \in U(x)$ such that for every $y \in F(q(x))$, the point x belongs to the interior of the set $F^{-1}(D(y, \varepsilon))$.

Clearly, each l.s.c. map is quasi l.s.c.: it suffices to put q(x) = x. For examples of quasi l.s.c., non l.s.c. mappings see [6], [10]. Possibly, one of the simplest examples is given by the mapping $F: X \to [0, \infty)$, F(x) = [0, l(x)], where

 $l: X \to [0, \infty)$ is an arbitrary singlevalued locally positive function. We need two Gutev's theorems [6]. Recall that for a multivalued mapping $F: X \to Y$ between topological spaces its *derived* mapping $F': X \to Y$ is defined by setting F'(x) to be equal to the set of all $y \in F(x)$, for which x belongs to the interior of the preimage (with respect to F) of every neighborhood of y (see [3]).

Theorem 2.3. Let $F: X \to Y$ be a closed valued quasi lower semicontinuous mapping of a topological space X into a complete metric space (Y, ρ) . Then the derived mapping $F': X \to Y$ is a lower semicontinuous selection of F with nonempty closed values. Moreover, if $G: X \to Y$ is a lower semicontinuous selection of F, then G is also a selection of F'.

Theorem 2.4. A mapping $F: X \to Y$ of a topological space X into a complete metric space (Y, ρ) is quasi lower semicontinuous if and only if for every triple $(x, U(x), \varepsilon)$, where $x \in X$, U(x) is a neighborhood of x and $\varepsilon > 0$, there exists a point $q(x) \in U(x)$ such that $F(q(x)) \subset D(F'(x), \varepsilon)$.

Finally, for each function $M:(0,\infty)\to [0,1)$ we define the following sequence of functions:

$$M_0(t) \equiv 1, M_1(t) = M(t), \ldots, M_{n+1}(t) = M(M_n(t) \cdot t) \cdot M_n(t), \ldots$$

Lemma 2.5. Let $M:(0,\infty)\to [0,1)$ be a nondecreasing function. Then for every positive τ , the series $\sum_{n=0}^{\infty} M_n(t)$ uniformly converges on the interval $(0,\tau)$.

3. Proof of Theorem 1.2

Under assumptions of the theorem, let $F: X \to Y$ be a given LS_{λ} -mapping. Then F is an LS_{∞} -mapping and, hence, has a lower semicontinuous closed-valued selection, say G. Let $f_0: X \to Y$ be an arbitrary singlevalued continuous mapping. Then the distance $d(x) = \operatorname{dist}(f_0(x), G(x))$ is an upper semicontinuous real-valued function on the paracompact space X. By the Dowker theorem, the function $d(\cdot)$ has a strong continuous singlevalued majorant, say $\varepsilon: X \to (0, \infty)$. Clearly, f_0 is an ε -selection of F. Now, for every natural number n we put:

$$R_n(x) = M_n(\varepsilon(x)) \cdot \varepsilon(x), \qquad r_n(x) = \lambda(R_n(x)) \cdot R_n(x),$$

where $M:(0,\infty)\to [0,1)$ is a fixed nondecreasing majorant of the function

$$t \mapsto \alpha(\lambda(t) \cdot t) \cdot \lambda(t)$$

and functions $M_n(\cdot)$ are defined above, before Lemma 2.5. Due to the continuity of the mapping $\epsilon: X \to (0, \infty)$ and due to Lemma 2.5, for every $x \in X$, there

exists its neighborhood U(x) such that the series $\sum_{n=0}^{\infty} R_n(\cdot)$ uniformly converges on U(x). Similarly, the series $\sum_{n=0}^{\infty} r_n(\cdot)$ uniformly converges on U(x), because of local boundedness of the function $\lambda(\cdot)$.

Let us construct a sequence of singlevalued continuous mappings $f_n: X \to Y$ with the properties that for each natural n and for each $x \in X$:

- (a_n) $d_n(x) = \operatorname{dist}(f_n(x), F(x)) < R_n(x);$ and
- $(b_n) \qquad \operatorname{dist}(f_{n+1}(x), f_n(x)) \leq r_n(x).$

We then see from (b_n) that there exists a pointwise limit $f = \lim_{n \to \infty} f_n$ and that f is a locally (and, hence globally) continuous mapping, due to the local uniform convergence of the series $\sum_{n=0}^{\infty} R_n(\cdot)$ and $\sum_{n=0}^{\infty} r_n(\cdot)$. The closedness of F(x) and inequalities (a_n) imply that f is a selection of F.

So, the mapping f_0 was constructed so that the inequality (a_0) holds. Suppose that for some n>0, we have mappings f_0, f_1, \ldots, f_n for which the inequalities $(a_0), (a_1), \ldots, (a_n)$ and $(b_0), (b_1), \ldots, (b_{n-1})$ hold. By (a_n) , the mapping f_n is an R_n -selection of F. Moreover, each nondecreasing mapping $M:(0,\infty)\to [0,1)$ has a continuous majorant $M_1:(0,\infty)\to [0,1)$, i.e. without loss of generality one can assume that $M(\cdot)$ from the hypotheses of the theorem is a continuous function. Hence, the functions $R_n(x)=M_n(\varepsilon(x))\cdot \varepsilon(x)$ are also continuous and it is possible to use Definition 1.1 of LS_{λ} -mappings, which directly shows that the mapping

$$x \to Cl(F(x) \cap D(f_n(x), \lambda(R_n(x)) \cdot R_n(x))) = Cl(F(x) \cap D(f_n(x), r_n(x)))$$

admits a lower semicontinuous selection, say G_n . By the classical Michael selection theorem [7], the mapping $Cl(\text{conv}(G_n))$ admits a singlevalued continuous selection, say f_{n+1} . Then

$$f_{n+1}(x) \in Cl(\operatorname{conv}(G_n(x))) \subset Cl(D(f_n(x), r_n(x))),$$

i.e. the inequality (b_n) holds. Now, using Definition 2.1 of the function of non-convexity for open balls $D(f_n(x), r_n(x))$ and remembering that $\alpha(\lambda(t) \cdot t) \cdot \lambda(t) < M(t)$ for all positive t, we see that:

$$\begin{aligned} \operatorname{dist}(f_{n+1}(x), F(x)) &\leq \alpha_{F(x)}(r_n(x)) \cdot r_n(x) \\ &\leq \alpha(\lambda(R_n(x)) \cdot R_n(x)) \cdot \lambda(R_n(x)) \cdot R_n(x) \\ &\leq M(R_n(x)) \cdot R_n(x) \\ &= M(M_n(\varepsilon(x)) \cdot \varepsilon(x)) \cdot M_n(\varepsilon(x)) \cdot \varepsilon(x)) \\ &= M_{n+1}(\varepsilon(x)) \cdot \varepsilon(x) = R_{n+1}(x), \end{aligned}$$

i.e. the inequality (a_{n+1}) holds. Theorem 1.2 is thus proved.

Remark. Clearly,

$$\operatorname{dist}(f_0(x),f(x)) \leq \sum_{n=0}^{\infty} r_n(x).$$

4. Proofs of Theorems 1.3-1.5

The initial step of the proofs represents the following lemma, which resulted from our discussions with Gutev.

Lemma 4.1. Let $F: X \to Y$ be a quasi lower semicontinuous mapping of a topological space X into a complete metric space (Y, ρ) , $f: X \to Y$ a single-evalued continuous mapping and $c(\cdot)$ a strong majorant for the distance function $d = \operatorname{dist}(f, F)$. Suppose that the interval-valued mapping $x \mapsto (d(x), c(x))$, $x \in X$, admits a single-valued continuous selection. Then for every $x \in X$, the intersection $F'(x) \cap D(f(x), c(x))$ is nonempty.

Proof. Let $s: X \to (0, \infty)$ be a continuous mapping such that d(x) < s(x) < c(x), for every $x \in X$. Pick a point $x \in X$ and put $\varepsilon = (c(x) - s(x))/2$. Let V = V(x) be a neighborhood of x such that the restriction of $s(\cdot)$ onto V is less than (c(x) + s(x))/2. Due to the continuity of f, find a neighborhood U = U(x) such that $f(x) \in D(f(z), \varepsilon)$, for every $z \in U$. We can apply Theorem 2.4 to the triple $(x, V \cap U, \varepsilon)$, i.e. we can find a point $g(x) \in V \cap U$ such that

$$F(q(x)) \subset D(F'(x), \varepsilon).$$

By invoking the inequality d < s, we see that

$$f(q(x)) \in D(F(q(x)), s(q(x))) \subset D(F'(x), s(q(x)) + \varepsilon).$$

Hence the inequality s(q(x)) < (c(x) + s(x))/2, implies that

$$f(x) \in D(f(q(x)), \varepsilon) \subset D(F'(x), s(q(x)) + 2\varepsilon) \subset D(F'(x), c(x)),$$

i.e. the distance between f(x) and F'(x) is less than c(x).

Proof of Theorem 1.3. Let $F: X \to Y$ be a quasi lower semicontinuous mapping of a topological space X into a complete metric space (Y,ρ) , $f: X \to Y$ a singlevalued continuous ε -selection of F, for some continuous function $\varepsilon: X \to (0,\infty)$, and $\lambda: (0,\infty) \to (1,\infty)$ a singlevalued continuous function. Then for the (continuous!) strong majorant $c(x) = \lambda(\varepsilon(x)) \cdot \varepsilon(x)$ of the distance function $d(x) = \operatorname{dist}(f(x), F(x))$, there exists an obvious continuous function $s(\cdot)$ which separates $d(\cdot)$ and $c(\cdot)$. Namely, $s(x) = \varepsilon(x)$. Lemma 4.1 shows that the mapping $G = F' \cap D(f,c)$ has nonempty values. But the derived mapping F' is a selection of F. Hence, G is a selection of the mapping $F \cap F'$

D(f,c). Lower semicontinuity of G follows from the lower semicontinuity of F' (see Theorem 2.3), from continuity of f, and from continuity of $c(\cdot)$. Thus we conclude that the mapping $x \mapsto F(x) \cap D(f(x), \lambda(\varepsilon(x)) \cdot \varepsilon(x))$ admits a lower semicontinuous selection. Theorem 1.3 is thus proved.

Proof of Theorem 1.4. Because of Theorems 1.2 and 1.3 it suffices to check the following simple fact:

Lemma 4.2. For every nondecreasing function $\alpha:(0,\infty)\to[0,1)$, there exists a continuous function $\lambda:(0,\infty)\to(1,\infty)$ such that the function $\alpha(\lambda(t)\cdot t)\cdot \lambda(t)$ has a nondecreasing strong majorant $M:(0,\infty)\to[0,1)$.

Proof. It is easy to find a *continuous* nondecreasing majorant $\beta:(0,\infty)\to [0,1)$ of the function $\alpha(\cdot)$ such that $\lim_{t\to\infty}\beta(t)=1$. Let $\beta(\cdot)<\gamma(\cdot)< M(\cdot)<1$ and the functions $\gamma(\cdot)$ and $M(\cdot)$ be both continuous and nondecreasing. We claim that $\lambda(\cdot)$ can then be defined as follows:

$$\lambda(t) = \frac{1}{2} \cdot \left(1 + \min\left\{\frac{M(t)}{\gamma(t)}, \frac{\beta^{-1}(\gamma(t))}{t}\right\}\right).$$

Clearly, $\lambda(\cdot)$ is continuous and greater than 1. Moreover,

$$\lambda(t) \cdot t < \beta^{-1}(\gamma(t)),$$
 $\alpha(\lambda(t) \cdot t) \le \beta(\lambda(t) \cdot t) < \gamma(t)$

and

$$\alpha(\lambda(t) \cdot t) \cdot \lambda(t) < \gamma(t) \cdot \lambda(t) < M(t)$$

due to the choice of $\lambda(t)$. Lemma 4.2 (and hence Theorem 1.4) are thus proved.

Sketch of the proof of Theorem 1.5. First, we refer to [16] for the proof that the hypotheses (b) and (c) together imply the quasi lower semicontinuity of the mapping F in two variables and, moreover, of the composition F(x, h(x, y)), for each continuous $h: X \times Y \to Y$. Second, (d) implies that $\gamma/(1-\alpha) < 1$ and hence for some numbers $M \in (\alpha, 1)$ and $\lambda > 1$, we have that $\gamma/(1-M) < 1$ and $\gamma \cdot \lambda/(1-M) < 1$.

Now the special case of the selection Theorem 1.2, when α, λ and M are constants, works for the α -paraconvex valued mapping $F_0 = F$ and we can find a selection of F_0 , say f_1 . Moreover, starting by $f_0(x, y) = y$, we have (see Remark after proof of Theorem 1.2),

$$\operatorname{dist}(f_0(x,y),f_1(x,y)) \leq \sum_{n=0}^{\infty} r_n(x,y) = \lambda \cdot \sum_{n=0}^{\infty} M^n \cdot \varepsilon(x,y) = \frac{\lambda}{1-M} \cdot \varepsilon(x,y),$$

for some continuous singlevalued $\varepsilon: X \times Y \to (0, \infty)$.

Put $F_1(x,y) = F_0(x, f_1(x,y))$ and let us estimate the distance between f_1 and F_1 :

$$\begin{aligned} \operatorname{dist}(f_1(x,y),F_1(x,y)) &\leq H_{\operatorname{dist}}(F_0(x,y),F_0(x,f_1(x,y))) \\ &\leq \gamma \cdot \operatorname{dist}(f_0(x,y),f_1(x,y)) \\ &< \gamma \cdot \frac{\mu}{1-M} \cdot \varepsilon(x,y); \qquad \lambda < \mu. \end{aligned}$$

Hence f_1 is an ε_1 -selection of F_1 with

$$\varepsilon_1(x,y) = \gamma \cdot \frac{\mu}{1-M} \cdot \varepsilon(x,y).$$

Reapplying Theorem 1.2, we find a selection of F_1 , say f_2 , with

$$\operatorname{dist}(f_1(x,y),f_2(x,y)) \leq \gamma \cdot \frac{\lambda}{1-M} \cdot \varepsilon_1(x,y) < \gamma^2 \cdot \frac{\mu^2}{(1-M)^2} \cdot \varepsilon(x,y).$$

Continuation of this procedure yields the estimate

$$\operatorname{dist}(f_n(x,y),f_{n+1}(x,y)) < q^{n+1} \cdot \varepsilon(x,y), \qquad q = \frac{\gamma \cdot \mu}{1-M}.$$

Having $\gamma \cdot \lambda/(1-M) < 1$, it is clear that we can assume that $\mu > \lambda$ and q < 1.

Remark. For the functions α and γ of nonconvexity and contractivity one can replace the hypotheses (d), i.e. the numerical inequality $\alpha + \gamma < 1$ by some functional expression.

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